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(54) Title: MINIATURE OPTICAL SENSOR			
(57) Abstract			
A miniature laser Doppler probe includes a laser, lens, another lens with a diffraction grating etched thereon, and a focusing lens. The focusing lens focuses the diffraction grating on an interrogation volume which has the particles whose movement is to be detected.			

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MINIATURE OPTICAL SENSORCross Reference To Related Applications

This application claims the benefit of the U.S. Provisional Application No. 60/102,151, filed on September 28, 1999.

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Statement as to Federally Sponsored Research

The invention described herein was made in the performance of work under a NASA contract, and is subject to the provisions of Public Law 96-517 (35 U.S.C. 202) in which the Contractor has elected to retain title.

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Background

Velocimeters detect velocity of moving elements. They are used in various applications. A miniature velocimeter can be used for detecting particle motion such as in industrial and medical applications. Velocimeters can also be used to detect macro motion, such as detecting the roughness of a surface, for example. Various other industrial applications are possible; such as detecting movements of belts, or the motion of a surface via its surface roughness, for example.

Laser Doppler velocimeters are commercially available. Such systems, are described, for example, in U.S. Patent Nos.

5,557,407; 5,552,879; 5,483,332; 5,587,785; 5,013,928; 5,216,478;
5,187,538; 5,737,070; 5,199,298; 4,896,098; and 5,052,228. These
generally use a gas laser and discrete optics. The instrument is
large and not susceptible for easy relocation. The instruments
5 are fragile, and typically not suitable for application in harsh
environments.

Optical systems of this type have required beam alignment
for the transmitting optics. Vibration and temperature changes
can cause misalignment in such systems.

10 A diode-based laser velocimeter has been suggested. This
could result in a smaller, more integrated probe.

Summary

The present application describes a self aligning optical
15 probe with a reduced element count and a relatively small overall
size. The probe can be used in environments that were not
previously accessible with such a device.

In one embodiment, a laser velocimeter probe is defined that
has a housing defining an interior chamber, and having first and
20 second ends, a laser source, located in the housing and directed
toward the second end, and an optical element, also located in
said housing between said laser and the second end. The optical

element includes at least a focusing element and a grating. A light receiver is also located in the housing, and receives scattered light from a direction of the second end.

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Brief Description of the Drawings

These and other aspects of the invention will be described in detail with reference to the accompanying drawings, wherein:

Figure 1 shows a block diagram of the components used in the embodiment of the sensor;

10 Figure 2 shows an optical path in the actual design execution of the sensor;

Figure 3 shows a outside view of the sensor;

Figure 4 shows a block diagram of a two-component sensor;

15 Figure 5 shows a block diagram of a frequency-shifting sensor.

Description of the Embodiments

Figures 1 and 2 show block diagrams of an embodiment.

The housing 98 in this embodiment is preferably sealed at both ends. First end 102 has a connector 202 that interfaces 20 with wires that go in and out of the sensor. These wires carry the power and the signals indicative of the operation carried out

by the sensor. A second end 104 is optically transparent, and is made out of, for example, optical glass.

A diode laser 100 produces an output laser beam which is focused on a beam splitter 120 via focusing optics, e.g. a 5 collimating lens 110. This beam splitter 120 is a diffraction grating or more generally a Diffractive Optical Element (DOE). A second imaging optics element 130 images the fringe pattern from the diffraction grating 120 at a probe volume 400. The object to be characterized will be located at the probe volume 400.

10 Another embodiment forms the diffraction pattern on the lens itself, e.g., on a surface of the lens 110. By etching the diffraction grating on the lens itself, much of the need for the probe to be aligned is obviated.

15 The system uses well-known laser Doppler and anemometry techniques. The image formed at the probe volume 400 creates in space a fringe pattern. A particle or moving volume crossing this fringe pattern at the probe volume 400 will scatter light. This light coming from the probe volume is collected onto the detector 310 through the collecting optics 300.

20 The diode laser 100 can be any kind of small laser source at any wavelength with the correspondent optic and detector. 660nm, 830nm, 980nm diodes have been successfully used.

The probe volume can be seen as an image of the diffraction grating or as the interference of two coherent light beams. The grating can define, for example, a set of parallel fringes which is focused at the measurement location. This set of fringes allows measuring the speed of moving volumes, objects or particles at the interrogation volume. Since the probe can measure diverging fringes close to the probe surface, this also measures the gradient of the velocity. Wall shear stress for example can be inferred therefrom.

10 The reflected laser beams are received into the collecting optics 300, which can be a lens, or a receiving multimode optical fiber 140 which has a numerical aperture of 0.37, and a of 50 μm . This fiber is used to collect the scattered light and to transmit the collected, scattered light onto a detector.

15 The components, e.g. laser 100, lens 110, lens/grating 120, and lens 130, are preferably attached to inside wall 98 of housing 200. Hence, this system is assembled to form a self-aligning transmitting optical system. No moving components are provided, and no individual adjustment of the beams is necessary. Also, the techniques described herein enable miniaturization of the eventual system. The unit, shown in Figure 3, is about 1 inch in diameter.

No moving components are provided in this embodiment, and no individual adjustment of the beams is necessary. The signal to the detector is on electrical connector 202, which can connect to one or many wires that emerge from the housing. This signal is 5 based on the scattered light of the particle or moving volume. The signal is related to the speed of the moving element, and that speed can be inferred therefrom using known techniques.

Other modifications are also possible. A first modification shown in Figure 4 allows measuring two different velocities at 10 the same time. This duplicates all components to form two sensors in the one housing 320. The first device 300 measures a first velocity and device 310 measures a second velocity, hence simultaneously measuring both velocity components. The device has a single connector 302 for commonly powering both devices 15 300, 310. Individual cables can return the velocity values.

The system as shown in Figure 4 uses a common probe volume to obtain a multicomponent sensor. Alternately, the probe volumes can be separate.

The probe can be adapted to allow phased Doppler or I_{max} 20 techniques to obtain a particle sizing probe.

Another embodiment describes using this system in a frequency-shifted probe technique as shown in Figure 5, which

uses a rotating diffractive optical element. A rotatable grating 510 is fabricated on a rotatable disk. A rotating element, e.g. a motor 500 driven by the power supply, is coupled to rotate the diffraction grating 510. This causes a rotating fringe pattern at the area of interest. Shifts in the measured frequency caused by the rotating pattern can provide directional sensitivity.

The system described herein has been described for use in conventional velocimeter components, e.g. movement of moving objects (particle, volume, surfaces...), wall shear stress measurement, and particle size measurement.

The system described herein has been described for use in conventional velocimeter components, e.g. movement of moving particles, moving macro portions, detecting surface roughness, and detecting wall shear stress. Another embodiment uses this in particle sizing. The basic design is integrated into a particle sizing probe, using well known phased Doppler and Imax techniques.

The overall optical system also minimizes the number of elements without using moving components (except for the frequency shifted probe), and without the need for beam alignment optics.

Other embodiments are within the disclosed invention.

What is claimed is:

1. A laser velocimeter probe, comprising:

a housing defining an interior chamber, and having first and second ends;

5 a laser source, located in said housing and directed toward said second end;

an optical element, also located in said housing between said laser and said second end, said optical element including at least a focusing element and a grating; and

10 a light receiver, also located in said housing, and

receiving scattered light from a direction of said second end.

2. A probe as in claim 1 further comprising a second lens

assembly, coupled between said optical element and said second

15 end, and positioned to focus laser light which has passed through said grating towards an area of said second end.

3. A probe as in claim 2 wherein an interrogation volume is defined at said second end.

4. A probe as in claim 3 wherein said second end is formed of optical glass.

5. A probe as in claim 1 wherein said laser source and said optical element are coupled to said housing to allow a constant spacing therebetween.

6. A probe as in claim 1 wherein said housing is hermetically sealed.

7. A probe as in claim 6 further comprising an optical processor, processing said scattered light to determine movement information therefrom.

8. A probe as in claim 1 wherein said diffraction grating includes a set of parallel fringes.

9. A probe as in claim 1 further comprising an element which moves said grating to provide directional sensitivity.

15 10. A probe as in claim 9 wherein said moving includes rotating.

11. A probe as in claim 1, wherein said grating is formed on a surface of said lens.

12. A probe as in claim 1, further comprising an electrical connector, receiving power, and providing electrical interface,
5 located at said first end.

13. A probe as in claim 12 further comprising a second probe inside said housing, located to measure a different velocity at a different area, said second probe also using said electrical connector.

10 14. A probe as in claim 13, wherein said housing is cylindrical, and is approximately 1 inch in diameter.

15 15. A self contained velocimeter probe, comprising:
a housing, having an exterior and an interior, said interior including at least one wall surface, and having a first end defining a signal interfacing surface, a second end having at least a portion formed of an optically transparent material;
a miniature laser source, coupled to said wall surface;

a lens and diffraction grating assembly, also coupled to said wall surface and spaced from said laser source at predetermined distances to allow focusing of said laser source via said diffraction grating, onto an interrogation area near 5 said second end; and

an optical receiver, located near said second end, to receive scattered light from said interrogation area.

16. A probe as in claim 15 wherein said optical receiver is a multimode optical fiber.

10 17. A probe as in claim 15 wherein said lens includes a surface with a diffraction grating etched thereon.

15 18. A probe as in claim 17 wherein there are two of said lenses, a first of which has said diffraction grating, the other which is between said first lens with said diffraction grating and a second end, and operates to focus a view of the diffraction grating towards said second end.

19. A probe as in claim 15 further comprising a second device inside said housing.

20. A probe as in claim 17 wherein said further comprising an element which moves said diffraction grating.

21. A method of detecting motion, comprising:
integrating optical components including a diode, a grating
5 and optics, into a self contained housing, in a self aligned
manner; and
using said optical components to detect motion.

22. A method as in claim 21, wherein said using comprises,
focusing light from said diode, through said grating, onto a
10 volume, and
receiving, within said housing, scattered light therefrom.